

# High- and Low-thrust Lambert Targeters

## High-thrust (classic) Lambert Targeter

[Lancaster and Blanchard(1969)] formulated a unified form of Lambert's theorem already in 1969. In their paper they also made a few suggestions about how to make an algorithm with their findings, but their suggested method still required much user-involvement.

Two decades later, [Gooding(1990)] published a complete procedure implementing their method. His procedure enabled fully automated solutions without any need for manual tweaking, which makes it stand out from for example, the Universal Variables method [Vallado(2001)]. The procedure only requires that a root be found of an analytic function, which makes it also considerably more efficient than for example, Battin's method [Battin(1999)].

Gooding published this complete procedure as FORTRAN-77 code, which was (and still is) widely used in the field of orbit design and optimization. `lamberthigh.m`, one of the two files in this toolbox, is a complete and user-friendly Matlab implementation of his procedure.

`lamberthigh.m`

Usage:

```
[V1, V2] = lamberthigh(r1, r2, tf)
[V1, V2] = lamberthigh(r1, r2, tf, m)
[V1, V2] = lamberthigh(r1, r2, tf, m, mu)
[V1, V2] = lamberthigh(r1, r2, tf, m, mu, way)
```

Dependencies:

`halley.m`

`[V1, V2] = lamberthigh(r1, r2, tf)` finds the conic section that goes through the departure position  $\mathbf{r1} = [x_1, y_1, z_1]$  and the target position  $\mathbf{r2} = [x_2, y_2, z_2]$ , taking a time `tf` to do so. The results are the two so-called terminal velocity vectors `V1` and `V2`, which are the velocities in this conic section at the departure and target points, respectively.

By default, the departure- and target vectors are expected to be in [km], and the transfer time in [s]. The terminal velocities are also in [km/s].

For example,

```
[V1, V2] = lamberthigh([1, 0, 0]*150e6, [0, 1, 0]*150e6, 365*86400/4)
```

results in

```
V1(:, :, 1) =
```

```

-0.134681252611695  29.812157559007780      0
V2(:, :, 1) =
-29.812157559007780  0.134681252611695      0

```

which is (approximately) the Earth's orbital velocity at the two indicated points, in [km/s].

`lamberthigh(r1, r2, tf, m)` will solve the multi-revolution problem. In other words, a total of  $m$  complete revolutions are completed before arrival at `r2`. In this case, no solution might exist. In that case, the result will be `NaN`.

`lamberthigh(r1, r2, tf, m, mu)` will take the value of `mu` as the standard gravitational parameter of the central body. If empty or omitted, the default value is 132712439940, which is the standard gravitational parameter of the Sun, in [km<sup>3</sup>s<sup>-2</sup>]. This allows the user to change the central body to any other desired body.

This parameter also allows the user to change the default system of units. For example, if a value of `mu` is used in units of [AU<sup>3</sup>s<sup>-2</sup>], also the position vectors `r1` and `r2` will be expected in [AU]. Note that in this case, also the resulting velocities will be in [AU/s].

`lamberthigh(r1, r2, tf, m, mu, way)` allows the user to change the 'way' of the solution. If omitted or empty, both the short-way (`V1(:, :, 1)`, `V2(:, :, 1)`) and long-way (`V1(:, :, 2)`, `V2(:, :, 2)`) solutions to the problem are output. This string argument may be equal to 'short', in which case only the short-way solution will be returned, or 'long', in which case the long-way solution will result. The default is 'both', e.g., both solutions.

As a validation (and demonstration) of the proper functioning of this function, four different test cases have been tried, each showing a different feature of this function. The first case is the Earth-Earth example given previously. The second example is a transfer from the Earth to Venus, with Earth-departure on Jan-01-2010 and arrival at Venus on Mar-17-2010, showing the algorithm is fully 3-D compatible. The third example is a direct transfer from Earth to Jupiter, The departure and arrival dates (Jan-01-2015 and Jan-10-2016, respectively) have been selected to be quite unfavorable for such a transfer, to show that hyperbolic trajectories are also not a problem. The last example is a transfer from Earth to Mars, with one full revolution between departure (Mar-11-2005) and arrival (Aug-22-2009). This shows that also such problems are tackled automatically and without any problems.

The results for these four cases are shown in Figure 1. Note that both the long-and short ways are plotted for each test case.

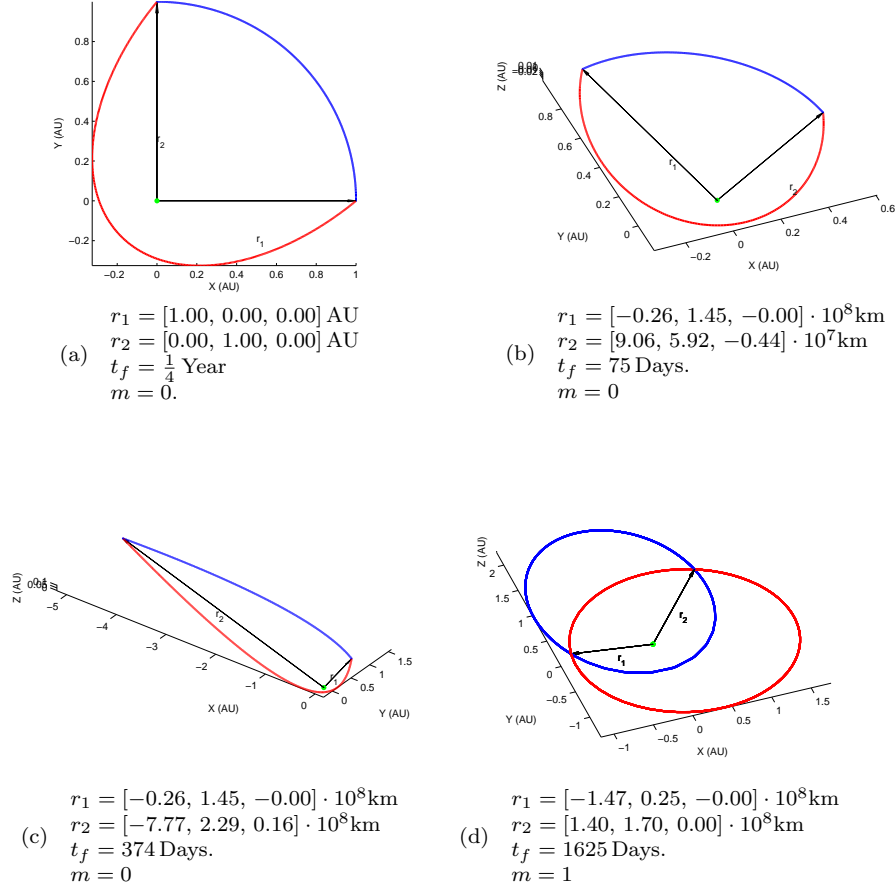


Figure 1: Various test cases for the high-thrust heliocentric Lambert-targeter. The blue line shows the short-way solution, and the red line depicts the long-way solution.

## Low-thrust (ExpoSin) Lambert Targeter

A.E. Petropoulos explored the possibility of using analytic representations of spirals in the analysis of low-thrust trajectories for his Ph.D. research. His findings, published in this dissertation which he completed in 2001 (see [Petropoulos and Longuski(2004)], although this is a publication based on it), show that a spiral trajectory described by an exponential sinusoid of the form

$$r = k_0 e^{k_1 \sin(k_2 \theta + \phi)}$$

is very well suited for this purpose. The equations associated with such trajectories can only be kept in closed-form when tangential thrust is assumed, which makes exponential sinusoids suited for first-order analysis only. In 2006, Dario

Izzo of the ESA Advanced Concepts Team derived the equations for the associated Lambert’s problem for exponential sinusoids [Izzo(2006)]. This procedure has been implemented in the second part of this small toolbox, `lambertlow.m`.

Usage:

```
[V1, V2, exposin] = lambertlow(r1, r2, tf)
[V1, V2, exposin] = lambertlow(r1, r2, tf, k2)
[V1, V2, exposin] = lambertlow(r1, r2, tf, k2, N)
[V1, V2, exposin] = lambertlow(r1, r2, tf, k2, N, mu)
[V1, V2, exposin] = lambertlow(r1, r2, tf, k2, N, mu, way)
```

Dependencies:

```
newtonraphson.m
regulafalsi.m
```

Note that the existence conditions for solutions are a lot stricter for an exponential sinusoid, so that in many cases no solution exists. In those cases, the result will be NaN.

`[V1, V2, exposin] = lambertlow(r1, r2, tf)` finds the exponential sinusoid that goes through the departure position  $\mathbf{r1} = [x_1, y_1, z_1]$  and the target position  $\mathbf{r2} = [x_2, y_2, z_2]$ , taking a time `tf` to do so. The results are the two so-called terminal velocity vectors `V1` and `V2`, which are the velocities at the departure and target point, respectively.

The `exposin` is the collection of parameters for the exponential sinusoid, in the format `exposin = [k0, k1, k2, phi, tf, N, dth, gamma1, gammam, gammaM]`.

The parameters `tf`, `N`, `dth`, `gamma1`, `gammam`, and `gammaM` (see [Izzo(2006)] for a definition) are appended for completeness or further analysis. The only parameters actually required for the exponential sinusoid are `k0`, `k1`, `k2`, and `phi`.

`lamberthigh(r1, r2, tf, k2)` will perform the procedure using a value of `k2` (the only independent variable—the winding parameter). By default, this value is taken equal to  $\frac{1}{12}$ .

`lamberthigh(r1, r2, tf, k2, N)` will solve the multi-revolution problem. In other words, a total of  $N$  complete spiral revolutions are completed before arrival at `r2`.

`lambertlow(r1, r2, tf, k2, N, mu)` will take the value of `mu` as the standard gravitational parameter of the central body. If empty or omitted, the default value is 132712439940, which is the standard gravitational parameter of the Sun, in  $[\text{km}^3\text{s}^{-2}]$ . This allows the user to change the central body to any other desired body.

This parameter also allows the user to change the default system of units. For example, if a value of  $\mu$  is used in units of  $[\text{AU}^3\text{s}^{-2}]$ , also the position vectors  $\mathbf{r}_1$  and  $\mathbf{r}_2$  will be expected in  $[\text{AU}]$ . Note that in this case, also the resulting velocities will be in  $[\text{AU}/\text{s}]$ .

`lambertlow( $\mathbf{r}_1$ ,  $\mathbf{r}_2$ ,  $t_f$ ,  $k_2$ ,  $N$ ,  $\mu$ ,  $\text{way}$ )` allows the user to change the 'way' of the solution. If omitted or empty, both the short-way (`V1(:, :, 1)`, `V2(:, :, 1)`, `exposin(:, :, 1)`) and long-way (`V1(:, :, 2)`, `V2(:, :, 2)`, `exposin(:, :, 2)`) solutions to the problem are output. This string argument may be equal to 'short', in which case only the short-way solution will be returned, or 'long', in which case the long-way solution will result. The default is 'both', e.g., both solutions.

As a validation (and demonstration) of the proper functioning of this function, two different test cases have been tried, showing a few different features of this function. The first case is again the simple Earth-Earth transfer, taking 2 years and 1 complete revolution. The second example is a random outbound trajectory from somewhere around the Earth to an out-of-plane target at about 5 AU, with 4 revolutions and a transfer time of 12 years.

The results for these two cases are shown in Figure 2. Note that both the long-and short ways are plotted for these test cases.

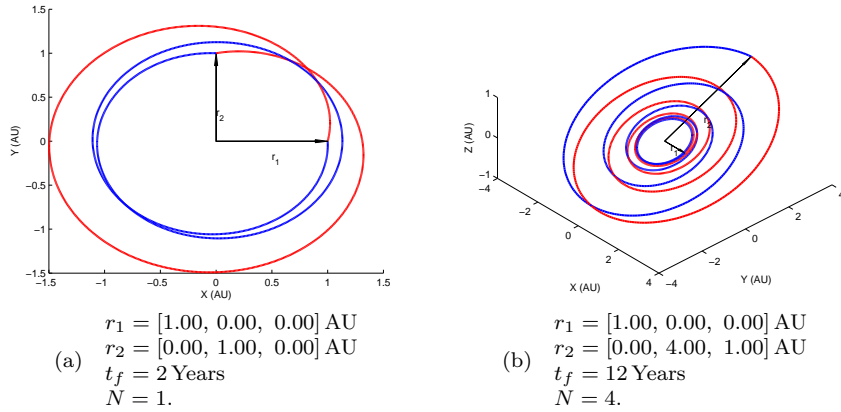


Figure 2: Two test-cases for the low-thrust Lambert targeter.

## References

[Battin(1999)] R.H. Battin. *An Introduction to the Mathematics and Methods of Astrodynamics, Revised Edition*. American Institute of Aeronautics and Astronautics, Virginia, 1999.

- [Gooding(1990)] R.H. Gooding. A procedure for the solution of lambert’s orbital boundary-value problem. *Celestial Mechanics and Dynamical Astronomy*, 48:145–165, 1990.
- [Izzo(2006)] D. Izzo. Lambert’s problem for exponential sinusoids. *Journal of Guidance Control and Dynamics*, 29:1242–1245, September 2006.
- [Lancaster and Blanchard(1969)] E.R. Lancaster and R.C. Blanchard. A unified form of lambert’s theorem. *NASA technical note TN D-5368*, 1969.
- [Petropoulos and Longuski(2004)] A.E. Petropoulos and J.M. Longuski. Shape-based algorithm for automated design of low-thrust, gravity-assist trajectories. *Journal of Spacecraft and Rockets*, 41:787–796, 2004.
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